RADFORE

TECHNICAL INSTRUCTIONS

INSTALLATION AND ADVANCED MAINTENANCE

HIGH SENSITIVITY AUDIO VOLTMETERS AND NOISEMETERS

1. GENERAL

2. CONTROLS, FUNCTIONS AND FACILITIES

- 2.1 Input Socket
- 2.2 D.C. Output Socket (HSV2, ANM2 and ANM3 only)
- Signal Output Socket
- Input Range Switch
- Battery Check Switch
- Noise Check Switch
- **External Weighting Switch** 2.7
- Weighting Selector Switches (Audio Noisemeters only)
- 2.9 Quasi-peak/r.m.s. Selector Switch (ANM3 only)

3. OPERATION

- 3.1 Setting Up
 3.2 Measurement

4. MAINTENANCE AND CALIBRATION

- 4.1 Maintenance
- 4.2 Calibration
 - Calibration of Module M3375 (HSV1 and ANM1) 4.2.1 and Module M3377 (ANM3)
 - Calibration of Module M3376 (HSV2 and ANM2)
 - 4.2.3 Calibration of Module M3374 (ANM1 and ANM2)

5. GUARANTEE

6. MODIFICATIONS

- 6.1 Modification to Measuring Amplifier M3373/1
- 6.2 Modification to Function Switch layout

1. GENERAL

The instrument is despatched from the factory fitted with its internal battery connected and ready for use. A description of the controls functions and facilities is described below, followed by operating details and maintenance and calibration procedures. This leaflet should be read in conjunction with the sales leaflet A53 which gives details of the instruments not repeated here.

2. CONTROLS, FUNCTIONS AND FACILITIES

2.1 Input Socket

The input impedance of the instrument is 1M ohm on all the measuring ranges except the -90db and -100db ranges where the impedance falls to approximately 820k ohms and 600k ohms respectively.

2.2 D.C. Output Socket (HSV2, ANM2 and ANM3

This socket provides a d.c. output proportional to the meter reading. The instrument is calibrated such that 1.00V D.C. appears at this outlet when 1.00V A.C. is fed into the voltmeter on the 0dBv range. Connection of a digital voltmeter on its 1 volt range will therefore provide a useful and precise alternative readout. 1.00V D.C. output is available on all input ranges corresponding to 0dBv.

2.3 Signal Output Socket

This socket permits inspection of the signal waveform prior to the meter amplifier. An output of 1 volt A.C. corresponds to f.s.d. (0dBv). The output source resistance has been chosen to be relatively high (2k7 ohms) in order that connection of a low impedance does not affect the accuracy of the meter reading.

2.4 Input Range Switch

By suitably combining the gain of the measuring amplifier and the attenuation of the input attenuator, 16 measuring ranges are provided. On some ranges the residual noise with the input short circuited will just be apparent e.g. on the 10μV range.

2.5 **Battery Check Switch**

Depression of this switch connects the meter to indicate the on-load battery condition. The batteries should be replaced when the indication is outside the green area.

Noise Check Switch

This switch disconnects the input socket and short circuits the input of the instrument itself to ground. This enables the optimum position of the instrument in relation to external hum fields to be located or unsuitable connections in the measurement set-up to be detected by inspection of spurious signals at the output socket. (See 3.1 below)

2.7 External Weighting Switch

A weighting network of any desired characteristic may inserted into the signal path of both the voltmeter and noisemeter. A 5-way DIN socket is mounted on the rear panel and provides the input signal at 100mV level for the rated input of the range selected, at a source resistance of 1k ohm. The return from an external filter is fed to a buffer amplifier providing a 1M ohm input resistance. The DIN socket also provides a + and -9 volt supply from the internal batteries to energise active filter networks. On the ANM3 this switch is located below the DIN socket on the rear panel.

2.8 Weighting Selector Switches

Four weighting characteristics may be selected on the Audio Noisemeters. Curves of the four frequency response characteristics are shown in the A53 sales leaflet.

2.9 Quasi-peak/r.m.s. Selector Switch (ANM3 only)

This switch selects the meter drive circuit. In the OUT position the instrument indicates true r.m.s. values on all wave forms. In the IN position the instrument is peak sensing but calibrated to read r.m.s. values on a sine wave. The pulse response of the circuit conforms with DIN 45 405 - Noise meter for Electro-acoustic Wideband circuits para 3.5.1 (Dynamic properties, Peak Value Indication).

3. OPERATION

3.1 Setting Up

It is important when using a system with an overall gain of up to 100dB that great care is taken both in the placement of the instrument in the laboratory and in the earthing layout of the measuring set up.

The instrument should be placed at a suitable distance from mains operated equipment such that the magnetic leakage field from the transformer does not induce hum in the low level circuitry of the voltmeter. Use of the 'Noise Check' button with the voltmeter's A.C. output connected to an oscilloscope will enable such induction to be seen.

The arrangement of earthing will also be found to be important when measuring at low levels. There are two conditions which may lead to erroneous readings. The first is when an earth loop exists in the measuring set up i.e. when more than one piece of apparatus is connected to a mains

(continued on back page)

DIAGRAMS

- Fig. 1 Layout underside view. Voltmeters and noisemeters.
 - 2 Plan view. Voltmeters and noisemeters except ANM3
 - 3 Plan view. ANM3 only.
 - 4 Measuring amplifer module M3373:

P.c.b. layout.

Circuit diagram.

Parts list.

5 Weighting amplifier module M3374 (noisemeters only) P.c.b. layout.

Circuit diagram.

Parts list.

- 6 Schematic diagram. Noisemeters only.
- Schematic diagram. Voltmeters only.
- 8 Meter amplifier module M3375 (average sensing): P.c.b. layout. Circuit diagram.

Parts list.

9 Meter amplifier module M3376 (true r.m.s. sensing): P.c.b. layout.

Circuit diagram.

Parts list.

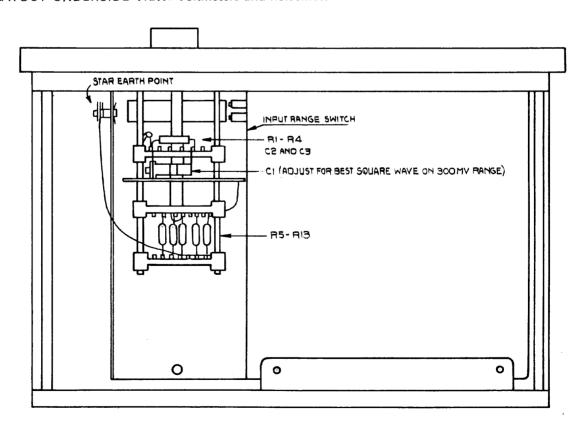
10 Quasi-peak rectifier module M3377 (ANM3 only):

P.c.b. layout.

Circuit diagram.

Parts list.

FIG. 1 LAYOUT UNDERSIDE VIEW. Voltmeters and noisemeters.



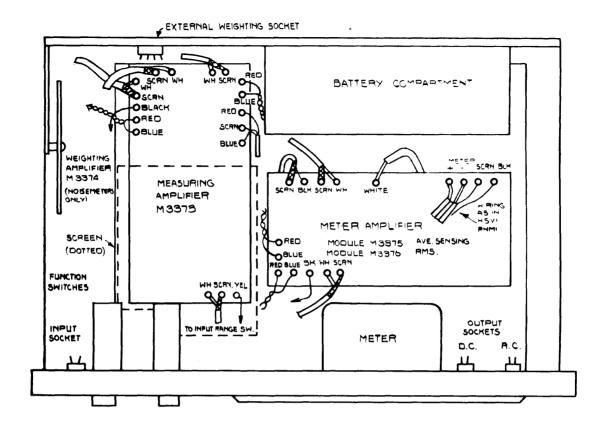
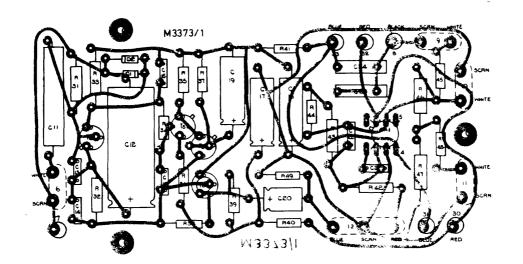
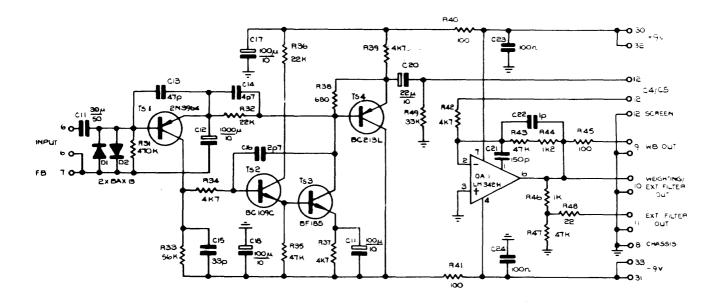


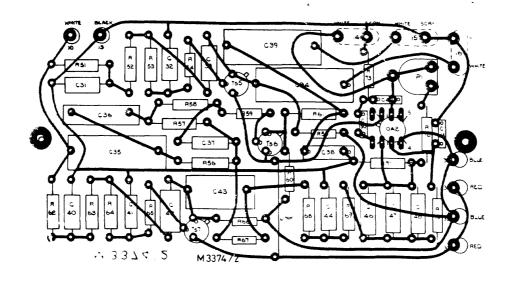
FIG. 3 PLAN VIEW. ANM3 only.

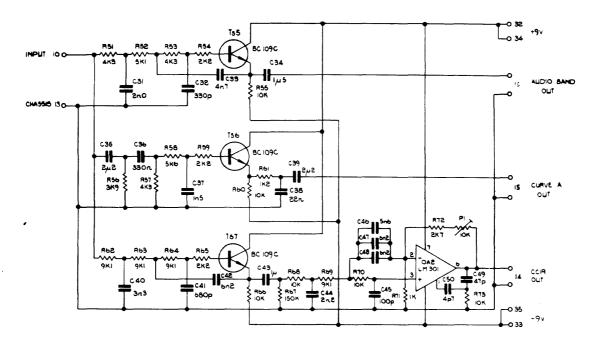






R31 R32 R33 R34 R35 R36 R37 R38 R39 R40 R41 R42 R44 R45 R44 R45 R47 R48 R49	MO MO MO CF CF CF See Text 6 CF MO MO CF CF MO CF CF	0.5W 0.5W 0.5W 0.25W 0.25W 0.25W 0.25W 0.25W 0.55W 0.55W 0.55W 0.55W 0.25W 0.55W 0.25W	470k 22k 56k 4k7 47k 22k 4k7 680R 100R 100R 4k7 47k 1k2 100R 1k 47k 22R 33k	2% 2% 2% 5% 5% 5% 5% 5% 5% 5% 5% 5% 5% 5% 5% 5%	C11 C12 C13 C14 C15 C16 C17 C18 C19 C20 C21 C22 C23 C24 TS1 TS2 TS3 TS4 D1 D2 OA1	E (REV.) E CR CR CR E E E CR CR PR PR 2N3964 BC109C BF185 BC213L BAX13 BAX13 LM318	30μF 1000μF 47pF 4.7pF 33pF 2.7pF 100μF 100μF 100μF 22μF 1.00μF 2.0 μF 2.0 μF 0.1 μF	50V 10V 63V 63V 63V 10V 10V 10V 10V 10V 10V 10V 10OV 10OV
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P1	HORIZOI	NTAL SKELETO	N PRESET	10k	TS6 TS7	ZTX109C ZTX109C		CA2	LM30
R73	CF	0.25W	10k	5%	TS5	ZTX109C	I		
R72	MO	0.5W	2k7	2%					
R71	MO	0.5W	1k	2%					
R70	MO	0.5W	10k	2%	C50	CR	4.7pF	63V	
R69	MO	0.5W	9k1	2%	C49	CR	47pF	63V	
R68	MO	0.5W	10k	2%	C48	PN	6200pF	100V	1%
R6#	CF	0.25W	150k	5%	C47	PN	6200pF	100V	1%
R66	ČF	0.25W	10k	5%	C46	PN	5600pF	100V	1%
R65	CF	0.25W	2k2	5%	C45	CR	100pF	63V	. 70
R64	MO	0.5W	9k1	2%	C44	PN	2200pF	100V	1%
R63	MO	0.5W	9k1	2%	C43	PR	1μF	100V	10%
R62	MO	0.5W	9k1	2%	C42	PN	6200pF	1007	1%
R61	MO	0.5W	1k2	2%	C41	PN	680pF	100V	1%
R60	ČF	0.25W	10k	5%	C40	PN	3300pF	100V	1%
R59	CF	0.25W	2k2	5%	C39	PR	2.2µF	100V	10%
R58	MO	0.5W	5k6	2%	C38	PR	0.022µF	100V	10%
R57	MO	0.5W	4k3	2%	C37	PN	1500pF	100V	1%
R56	MO	0.5W	3k9	2%	C36	PR	0.33µF	100V	10%
R55	ČF	0.25W	10k	5%	C35	PR	2.2μF	100V	10%
R54	CF	0.25W	2k2	5%	C34	PR	1.5µF	100V	10%
R53	MO	0.5W	4k3	2%	C33	PN	4700pF	100V	1%
R52	MO	0.5W	5k1	2%	C32	PN	330pF	100V	1%
R51	MO	0.5W	4k3	2%	C31	PN	2000pF	100V	1%

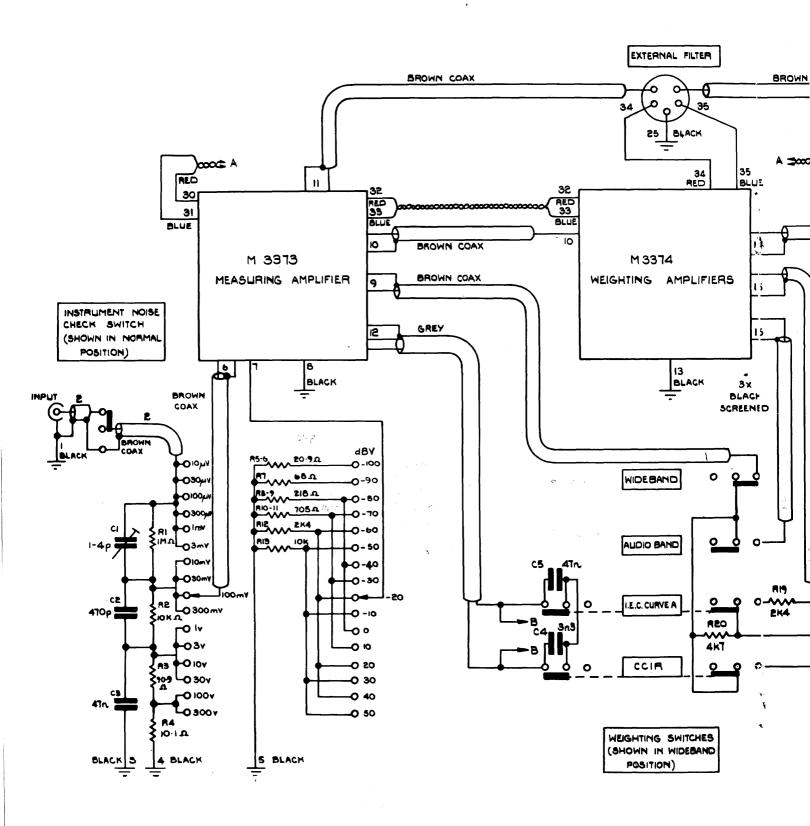
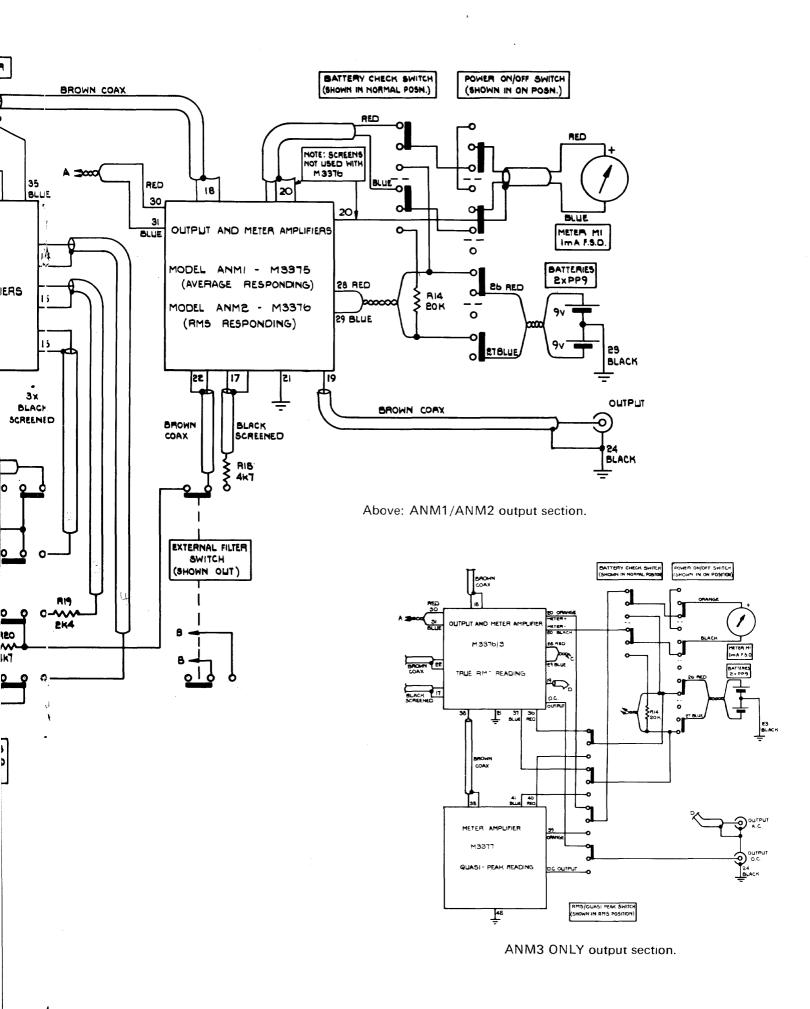


FIG. 6 SCHEMATIC DIAGRAM. Noisemeters only.



282222

TRIMMER 470pF 0.047µF 3300pF 0.047µF

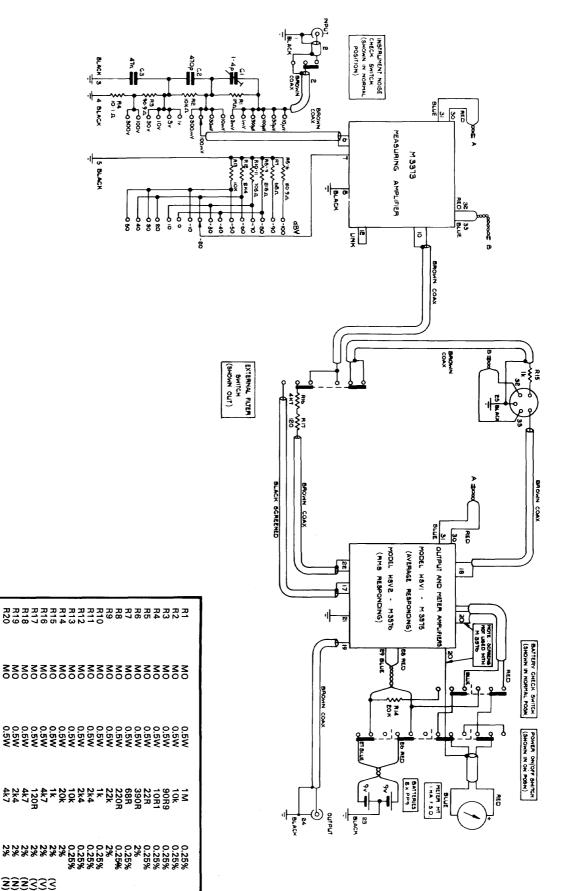
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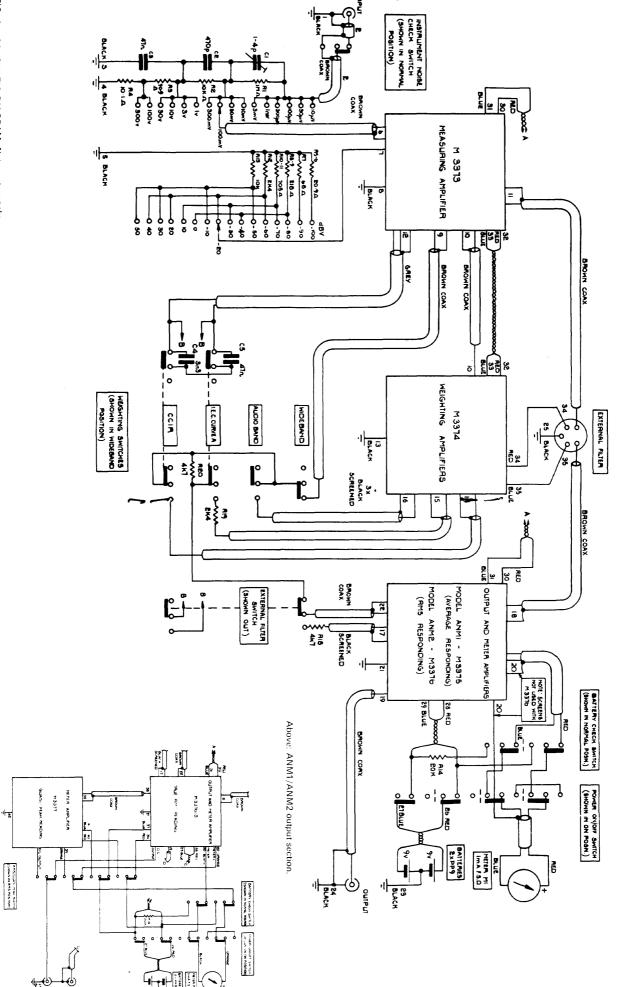
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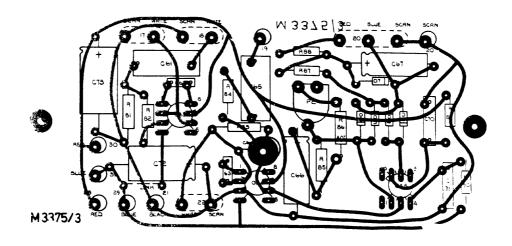
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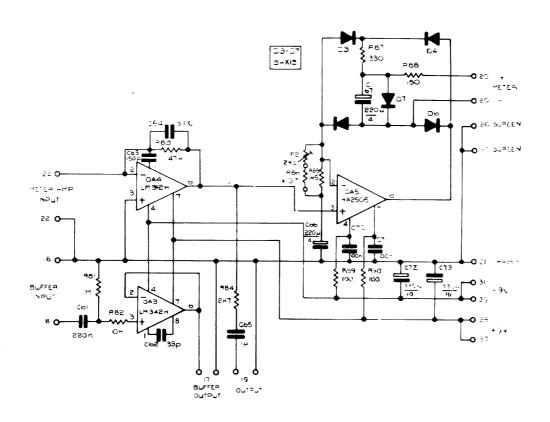
Voltmeters only. Noisemeters only.



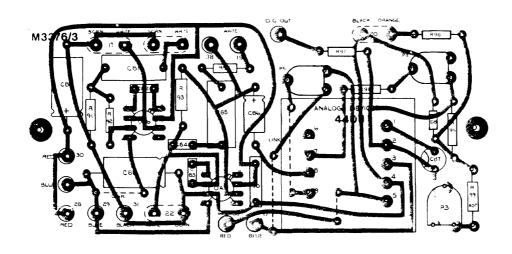


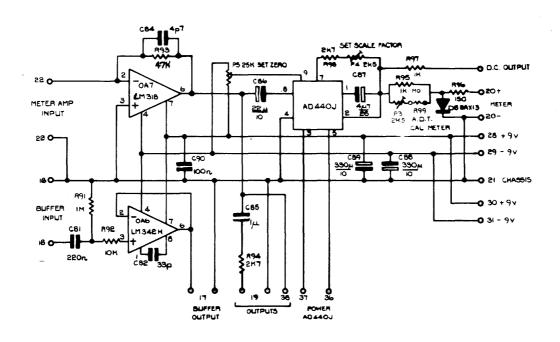
ANM3 ONLY output section.



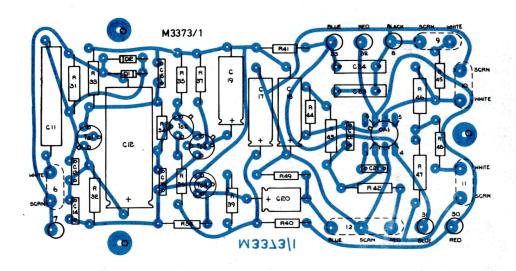


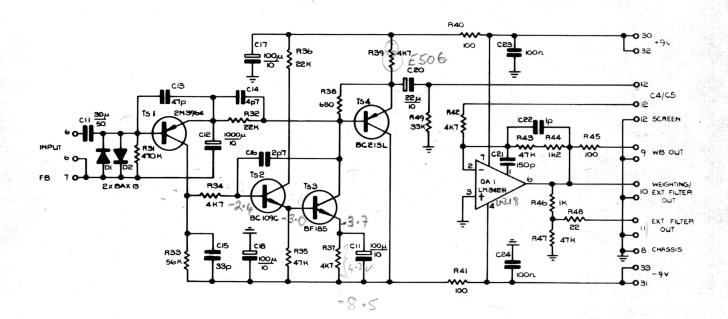
R81 R82 R83 R84	MO CF MO CF	0.5W 0.25W 0.5W 0.25W	1 M 10k 47k 2k7	2% 5% 2% 5%	P2	HORIZON	ITAL SKELETON	PRESET 2k	5
R85 R86 R87 R88 R89 R90	MO MO CF CF CF	0.5W 0.5W 0.25W 0.25W 0.25W 0.25W	1k2 A.O.T. 330R 150R 100R 100R	2% 2% 5% 5% 5% 5%	C61 C62 C63 C64 C65 C66 C67	PR CR CR PR E E	0.22µF 33pF 150pF 4.7pF 1µF 220µF 220µF	100V 63V 63V 63V 100V 4V 4V	10%
D3 D4 D5 D6 D7	BAX13 BAX13 BAX13 BAX13 BAX13		OA3 OA4 OA5	LM301 LM301 LM318	C68 C69 C70 C71 C72 C73	NOT USE NOT USE PR PR E E		100V 100V 10V 10V	10% 10%



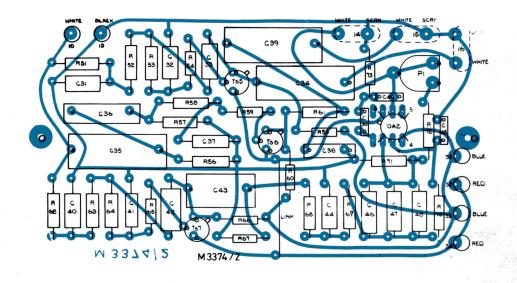


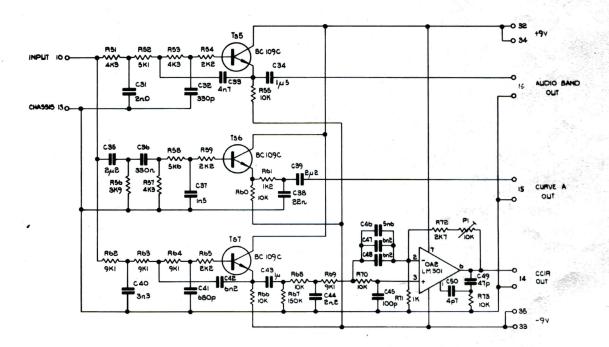
P3 P4 P5	HORIZON	NTAL SKELETO! NTAL SKELETO! NTAL SKELETO!	N PRESET	2k5 2k5 25k	0A6 0A7	LM301 LM318		D8	BAX13
					R.M.S. T	O D.C. CONVERT	TER: ANALO	G DEVICES	440J
Noo	IVIO	0.5**	A.O.1.	2.0	C90	PR	0.1μF	100V	10%
R98 R99	MO MO	0.5W 0.5W	2k7 A.O.T.	2% 2%	C88 C89	E	330µF 330µF	10V 10V	
R97	CF	0.25W	1 k	5%	C87	E (TANT.)	4.7μF	25V	
R96	CF	0.25W	150R	5%	C86	E	22μF	10V	
R95	MO	0.5W	1k	2%	C85	PR	1μF	100V	10%
R94	CF	0.25W	2k7	5%	C84	CR	A.O.T.	63V	
R92 R93	CF MO	0.25W 0.5W	10k 47k	5% 2%	C82 C83	CR NOT USED	33pF	63V	
R91	MO	0.5W	1M	2%	C81	PR	0.22μΓ	100V	10%



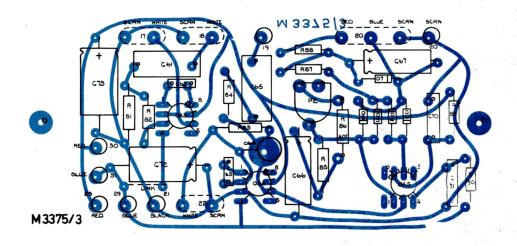


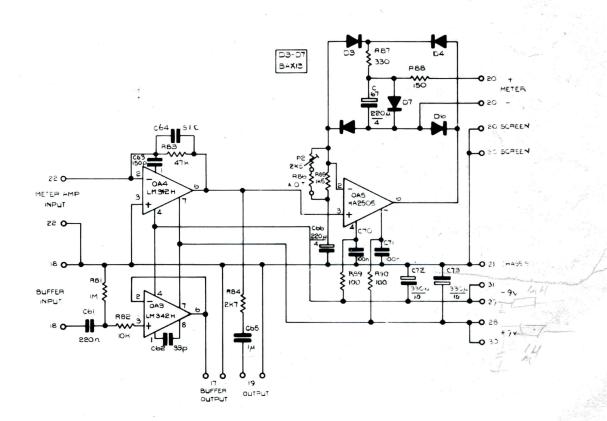
					C11	E (REV.)	30μF	50V
					C12	E	1000µF	10V
D04		0.5144	4701		C13	CR	47pF	63V
R31	МО	0.5W	470k	2%	C14	CR	4.7pF	63V
R32	МО	0.5W	22k	2%	C15	CR	33pF	63V
R33	МО	0.5W	56k	2%	C16	CR	2.7pF	63V
R34	CF	0.25W	4k7	5%	C17	E	100µF	10V
R35	CF	0.25W	47k	5%	C18	E	100µF	10V
R36	CF	0.25W	22k	5%	C19	E E	100µF	10V
R37	CF	0.25W	4k7	5%	C20	Ē	22μF	10V
R38	CF	0.25W	680R	5%	C21	CR	150pF	63V
R39	See Text 6				C22	CR	A _s O.T.	63V
R40	CF	0.25W	100R	5%	C23	PR	0.1µF	100V
R41	CF	0.25W	100R	5%	C24	PR	0.1μF	100V
R42	. MO	0.5W	4k7	2%	021		0.1 μ.	
R43	MO	0.5W	47k	2%	TS1	2N3964		
R44	CF	0.25W	1k2	5%	TS2	BC109C		
R45	CF	0.25W	100R	5%	TS3	BF185		
R46	MO	0.5W	1k	2%	TS4	BC213L		
R47	MO	0.5W	47k	2%	134	DCZIJL		
R48	CF	0.25W	22R	5%	D1	BAX13		
R49	CF	0.25W	33k	5%	D2	BAX13		
					52	DAXIS		
					OA1	LM318		



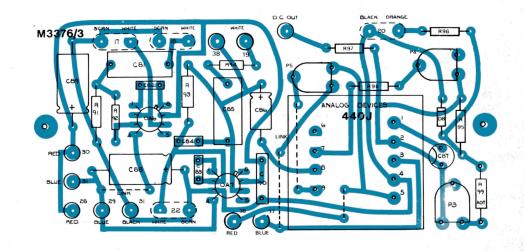


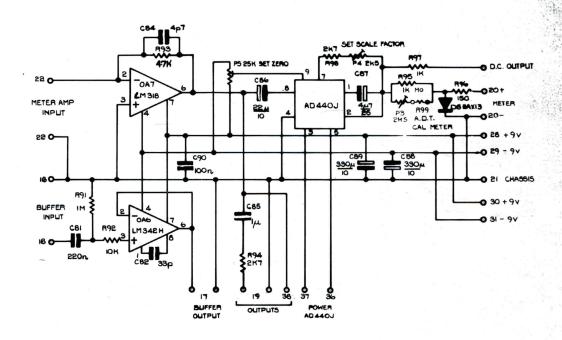
							and the second second		
R51	мо	0.5W	4k3	2%	C31	PN	2000pF	100V	1%
R52	MO	0.5W	5k1	2%	C32	PN	330pF	100V	1%
R53	MO	0.5W	4k3	2%	C33	PN	4700pF	100V	1%
R54	CF	0.25W	2k2	5%	C34	PR	1.5μF	100V	109
R55	CF	0.25W	10k	5%	C35	PR	2.2µF	100V	109
R56	MO	0.5W	3k9	2%	C36	PR	0.33µF	100V	109
R57	MO	0.5W	4k3	2%	C37	PN	1500pF	100V	1%
R58	MO	0.5W	5k6	2%	C38	PR	0.022µF	100V	109
R59	CF	0.25W	2k2	5%	C39	PR	2.2µF	100V	109
R60	CF	0.25W	10k	5%	C40	PN	3300pF	100V	1%
R61	MO	0.5W	1k2	2%	C41	PN	680pF	100V	1%
R62	MO	0.5W	9k1	2%	C42	PN	6200pF	100V	1%
R63	MO	0.5W	9k1	2%	C43	PR	1μF	100V	109
R64	MO	0.5W	9k1	2%	C44	PN	2200pF	100V	1%
R65	CF	0.25W	2k2	5%	C45	CR	100pF	63V	
R66	CF	0.25W	10k	5%	C46	PN	5600pF	100V	1%
R67	CF	0.25W	150k	5%	C47	PN	6200pF	100V	1%
R68	MO	0.5W	10k	2%	C48	PN	6200pF	100V	1%
R69	MO	0.5W	9k1	2%	C49	CR	47pF	63V	
R70	MO	0.5W	10k	2%	C50	CR	4.7pF	63V	
R71	MO	0.5W	1k	2%					
R72	MO	0.5W	2k7	2%	10				
R73	CF.	0.25W	10k	5%	TS5	ZTX109C			
					TS6	ZTX109C	1	CA2	LM30
P1	HORIZON	NTAL SKELETOI	N PRESET	10k	TS7	ZTX109C	200		





R81 R82 R83	MO CF MO	0.5W 0.25W 0.5W	1 M 10k 47k	2% 5% 2%	P2	HORIZON	ITAL SKELETON	PRESET 2k5	
R84 R85 R86 R87 R88 R89	CF MO MO CF CF CF	0.25W 0.5W 0.5W 0.25W 0.25W 0.25W 0.25W	2k7 1k2 A.O.T. 330R 150R 100R 100R	5% 2% 2% 5% 5% 5%	C61 C62 C63 C64 C65 C66	PR CR CR CR PR E	0.22μF 33pF 150pF 4.7pF 1μF 220μF 220μF	100V 63V 63V 63V 100V 4V	10%
D3 D4 D5 D6 D7	BAX13 BAX13 BAX13 BAX13 BAX13		OA3 OA4 OA5	LM301 LM301 LM318	C68 C69 C70 C71 C72 C73	NOT USE NOT USE PR PR E E	D	100V 100V 10V 10V	10% 10%





R91 R92 R93 R94	MO CF MO CF	0.5W 0.25W 0.5W 0.25W	1 M 10k 47k 2k7	2% 5% 2% 5%	C81 C82 C83 C84	PR CR NOT USED CR	0.22μF 33pF A.O.T.	100V 63V 63V	10%
R95 R96 R97 R98 R99	MO CF CF MO MO	0.5W 0.25W 0.25W 0.5W 0.5W	1k 150R 1k 2k7 A.O.T.	2% 5% 5% 2% 2%	C85 C86 C87 C88 C89	PR E E (TANT.) E E	1μF 22μF 4.7μF 330μF 330μF	100V 10V 25V 10V 10V	10%
					C90 R.M.S. T	PR O D.C. CONVER	0.1μF TER: ANALO	100V. G DEVICES	10% 440J
P3 P4 P5	HORIZON	NTAL SKELETON NTAL SKELETON NTAL SKELETON	PRESET	2k5 2k5 25k	0A6 0A7	LM301 LM318	5	D8	BAX13

earth or several pieces of equipment are connected in such a way that cable screens form a complete loop, causing circulating currents. The second condition occurs when the voltmeter is connected such that it provides the connection of the apparatus under test to mains earth.

3.2 Measurement

The average sensing (HSV1 and ANM1) and peak sensing (ANM3) instruments are calibrated to read the r.m.s. value with a sine wave input. Therefore, on all other waveforms, including random noise, there will be a difference between the observed reading and the true r.m.s. value.

It may be necessary when operating at low levels, to subtract the noise contribution of the measuring system from the total reading, in order to determine the value of the signal being measured. In most cases this contribution will be uncorrelated with the measured signal in which case they combine according to a square law.

Total reading $= J(Signal^2 + Noise^2)$

4. MAINTENANCE AND CALIBRATION

4.1 Maintenance

The schematic diagrams figs 6 and 7 show the wiring of the instruments external to the printed circuit board modules.

It is not intended that p.c.b. modules in the Voltmeters and Noisemeters be repaired by component replacement. They should be replaced by factory tested modules should a fault occur. Physical layout diagrams of the instrument, Fig. 2 provide identification of modules and other components assemblies. Printed circuit board modules are fitted with 'Amp' type connectors to facilitate easy replacement.

For completeness, and for emergency repair, printed circuit board module layout diagrams are included (figs 4-5 and 8-10) which show the copper circuitry in relation to the components. The module terminations are numbered and colour coded to ensure correct lead connection after board replacement.

Should you require advice or the supply of any component, module or sub-assembly please write to the Service Department, Radford Laboratory Instruments Limited, Bristol

4.2 Calibration

It may be necessary to re-calibrate the instrument either to comply with a laboratory maintenance schedule or in the event of error following mechanical shock. The range to range accuracy of the instrument is governed by high stability metal film resistors in the attenuator and measuring amplifier and is not adjustable. The overall accuracy of the instrument is set by adjustment to the meter amplifier board (either M3375, M3376 or M3377) as detailed below.

4.2.1 For average and Peak Sensing Instruments

(M3375 and M3377 meter amplifiers)

- (i) With instrument switched off, adjust mechanical zero of meter.
- (ii) Switch instrument to 'Wideband' and to the OdBv range and inject 1kHz sine wave at 1.00V r.m.s.
- (iii) Set P2 (P6 on M3377) midway. Select a value of metal oxide resistor for R86 (R111 on M3377) (usually between 4k7 and 10k) which adjusts meter reading to within 1% of f.s.d.
- (iv) Adjust P2 (P6 on M3377) to give precise f.s.d. (i.e. 0dBv)

4.2.2 For true r.m.s. Reading Instruments (M3376 meter amplifier)

(i) With instrument switched off, adjust mechanical zero of meter.

- (ii) Connect a d.c. Digital Voltmeter to the D.C. output of the instrument, select 'External Weighting' and adjust P5 for zero on DVM.
- (iii) Set instrument to 0dBv range and 'Wideband' weighting, inject 1kHz sine wave at 1.00 volts r.m.s. and set P4 for 1.00 volts D.C. on DVM.
- (iv) Set P3 midway, select a value of metal oxide resistor for R99 (usually between 4k7 and 10k) which adjusts meter reading to within 1% of f.s.d.

(v) Adjust P3 to give precise f.s.d. (i.e. 0dBv)

If no Digital Voltmeter is available, do not adjust P4 and P5 but employ calibration procedure consisting of Para. 4.2.1 (i) and (ii) followed by Para. 4.2.2 (iv) and (v).

4.2.3 Adjustment of CCIR weighting network (M3374) 0dB frequency

An adjustment is provided on the weighting amplifier board of the noisemeters so that the 0dB frequency of the CCHR weighting curve may be set to the required standard (either 1kHz or 2kHz). Instruments with serial numbers up to and including 701391 left the factory with the 0dB frequency set to 2kHz. Instruments from serial number 701401 are set to 0dB at 1kHz (see below for method of adjustment of frequency at 0dB response).

- Inject the required frequency sine wave at 1 volt r.m.s. with the instrument on the OdBv range to give precise f.s.d. on the wideband characteristic.
- (ii) Switch to 'CCIR' weighting and adjust P1 for precise

5. GUARANTEE

Home

This instrument is guaranteed for a period of one year from the date of purchase. It covers the free replacement or repair of any defective component or part of the equipment during this period. It also covers the cost of labour in executing the repair or replacement if the instrument is returned to the factory service department, carriage paid, within the guarantee period.

Overseas

It is generally not practicable to return the instrument to the factory in England and instruments will normally be maintained in a serviceable condition by the replacement of sub-assemblies, modules or specific component parts.

In the case of instruments purchased through an agent in a country outside the U.K., the agent will act for the manufacturer in that country. Service enquiries should therefore be directed to the agent. If the instrument is purchased direct from the factory in countries where there is no Radford agent, enquiries should be directed to the Service Department in Bristol.

6. MODIFICATIONS

6.1 Modification to Measuring Amplifier M3373/1

This modification is essential in order to maintain the accuracy specification of the instruments with changes in battery voltage. The resistor R39 (4k7) is replaced by a current source type E506 (Siliconix). Measuring amplifier modules designated M3373/2 incorporate this modification.

6.2 Modification to Function Switch layout

This modification concerns factory production only.

The Function Switches 'External Weighting' and 'Noise Check' are interposed in order to improve the wiring layout and marginally improve the stability of the voltmeter on the —90dB and —100dB ranges when driven from a high source impedance.

Radford Laboratory Instruments Limited.

4 High Street, Nailsea, Bristol BS19 1BW. Tel. (02755) 6637



Low Cost, General Purpose True RMS-to-DC Converter

MODEL 440

FEATURES

True RMS-to-DC Measurement
High Accuracy: 0.1% for C.F. ≤5
DC to 100kHz Response (1% Error)
All Hermetically Sealed Semiconductors
Low Cost:

APPLICATIONS
OEM RMS Instrumentation
Complex Waveform Measurements
SCR Controller & Power Line Measurements
Audio, Accoustic and Vibration Measurements
Mean Square Measurements
Random Thermal Noise Measurements

GENERAL DESCRIPTION

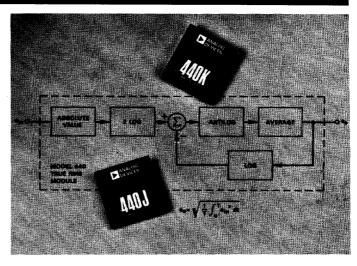
Model 440 is a compact economy RMS to DC converter module featuring performance usually found in higher priced units. In addition to measuring AC signals, model 440 can also measure directly the RMS value of a waveform containing both AC and DC. No external adjustments or components are required to achieve rated performance. For measurements below 100Hz, a single external capacitor may be added to achieve 0.1% accuracy without affecting the bandwidth for high frequency measurements.

Model 440 is available in two accuracy grades: model 440 K features total error of $\pm 5 \,\text{mV} \pm 0.1 \,\text{\%}$, while model 440 J has total error of $\pm 15 \,\text{mV} \pm 0.2 \,\text{\%}$. Optional external scale factor and offset voltage trimming will significantly reduce error for both models.

WHERE TO USE MODEL 440

OEM Instrument Designers will find the small size, low cost and high accuracy of model 440 makes it an excellent choice wherever RMS measurements must be made independent of waveform. This design offers significant accuracy improvements over the common rectifier-averaging type of meter. For example, the rectifier-averaging instrument has an error of 64% of reading on a 10% duty cycle pulse train, while the model 440 will provide less than 1% error by comparison. For industrial measurements, such as SCR motor controllers, as well as line voltage measurements, with high harmonic distortion, model 440 features high crest factor capability resulting in measurement errors less than ±1%.

The RMS value of any stationary zero-mean random signal is equal to the standard deviation (σ) of that signal. Accurate measurements of random signals, including acoustical noise, mechanical vibration and electrical noise are easily accomplished.



Model 440 may also be connected (see Figure 3) to measure the Mean Square of a signal ($e_0 = \overline{e_{in}^2}/V_R$). The Mean Square of a random signal is equal to the variance (σ^2).

TOTAL ACCURACY

Total output error is specified as the sum of two components; a fixed term plus a percentage of peak output signal. Model 440K, for example, has a rated accuracy of $\pm 5 \,\mathrm{mV} \pm 0.1 \,\mathrm{\%}$, which for a one volt RMS sinewave, results in a $\pm 6 \,\mathrm{mV}$ maximum error ($\pm 5 \,\mathrm{mV}$ fixed error plus $\pm 1 \,\mathrm{mV}$ reading error). The fixed error component is composed of output offset and input offset errors. The % of reading error is attributed to nonlinearity and scale factor errors. Scale factor error may be reduced by external adjustment of an optional $5 \,\mathrm{k}\,\Omega$ potentiometer (see Figure 2). Offset voltage can also be trimmed to zero by external adjustment of an optional $20 \,\mathrm{k}\,\Omega$ pot.

Accuracy is also dependent on the input signal frequency, amplitude and crest factor which are discussed in detail below.

HIGH FREQUENCY PERFORMANCE VERSUS SIGNAL LEVEL

grand the state of the state of

Shown in Figure 4 is a plot of reading error versus frequency with input signal amplitude as a parameter. This error arises because of internal limitations in slew rate capability for large signal levels. At small signal levels, slew rate limiting is not predominant. Therefore, to achieve best accuracy in wideband applications with model 440, the designer should consider scaling down the input signal to optimize performance as shown in Figure 4.

(continued on page 3)

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P.O. Box 280; Norwood, Massachusetts 02062 U.S.A. Telex: 924491 Cables: ANALOG NORWOODMASS

SPECIFICATIONS (typical @ $+25^{\circ}$ C and $V_s = \pm 15$ VDC, unless otherwise noted)

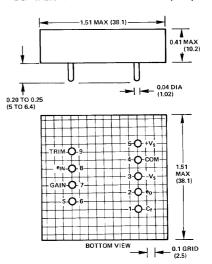
MODEL	440J	440K
TRANSFER EQUATION	$e_{\rm O} = \sqrt{\rm avg} \left(e_{\rm in}\right)^2$	*
ACCURACY		
Total Error ¹		
No External Adjustment	±10mV ±0.2%, Max	±5mV ±0.1%, Max
External Adjustment ²	±2mV ±0.1%, Max	±2mV ±0.05%, Max
vs. Temperature (0 to +70°C)	$\pm (0.2 \text{mV} \pm 0.02\%)/^{\circ} \text{C}, \text{Max}$	*
vs. Supply Voltage	±0.2mV/V	*
CREST FACTOR		
Rated Accuracy	5 Min	*
±1% Reading Error	10	*
FREQUENCY RESPONSE, Sineway	2	
Rated Accuracy		
Input Range, 0.1 to 7V _{rms}	10kHz, Min	*
±1% Reading Error		
Input, 7V _{rms}	50kHz, Min	*
Input, 0.7V _{rms}	50kHz, Min	*
Bandwidth, -3dB		
Input Range, 0.7 to 7V _{rms}	500kHz	*
Internal Filter Time Constant	10ms	*
External Filter Time Constant ³	50ms/μF	*
Total Averaging Time Constant	10ms + 50ms/μF	*
OUTPUT SPECIFICATIONS		
Rated Output ⁴		
Voltage	+10.0V, Min	*
Current	+10.0mA, Min	*
Resistance	0.1Ω	*
Offset Voltage	15. 33.35	+2
Internally Trimmed ⁵	±5mV, Max	±2mV, Max
External Trim	Adjustable to Zero	*
INPUT SPECIFICATIONS		
Voltage		
Signal Range	±10V, Peak	*
Safe Input	±V _S , Max	*
dB Range, Referred to 1V	-40dB to 17dB	*
dBm Range, referred to 0.775		*
(1mW in 600Ω)	-38dBm to 19dBm 8.3kΩ ±2%	
Impedance	8.3K12 ±2% ±1mV, Max	*
Offset Voltage	$\pm 1 \text{ mV}, \text{ Max}$ $\pm 10 \mu \text{V}/^{\circ} \text{C}$	*
vs. Temperature (0 to +70°C) POWER SUPPLY ⁶	±10μν/ C	
	+15VDC	*
Voltage, Rated Performance	±15VDC ±(6 to 18)VDC	*
Voltage, Operating	±(6 to 18)VDC ±10mA	*
Current, Quiescent	TIONA	·
TEMPERATURE RANGE	0 7000	
Rated Performance	0 to +70°C -25°C to +85°C	*
Operating	-25 °C to +85 °C -55 °C to +125 °C	*
Storage	-55 C to +125 C	
MECHANICAL	1.5" x 1.5" x 0.4"	•
Case Size		*
Mating Socket	AC1016	*
Weight	40g	

^{*}Specifications same as Model 440J.

Specifications subject to change without notice.

OUTLINE DIMENSIONS

Dimensions shown in inches and (mm).



MATING SOCKET AC1016

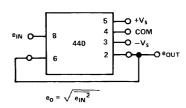
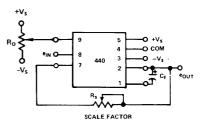


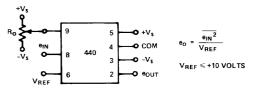
Figure 1. Wiring Connections for RMS Measurements (No External Trim)



 \mbox{R}_{S} = 5k\$\Omega\$, ANALOG DEVICES 79PR5k \mbox{R}_{O} = 20k\$\Omega\$, ANALOG DEVICES 79PR20k

Select C_f for increased averaging time constant. $(\tau(ms) = 10 + 50 \text{ C}_f (\mu F))$

Figure 2. Optional External Adjustment for RMS Measurements



 $R_D = 20k\Omega$, ANALOG DEVICES 79PR20k

Figure 3. Wiring Connections for Mean Square Measurements with Adjustable Scale Factor (V_{REF})

¹ Error is specified as the sum of two components: a fixed term plus a percentage of output signal. The fixed error component is composed of output offset error, and input offset error. The percentage of output signal (reading error) may be reduced by external adjustment of a scale factor potentiometer.

² See Figure 2 for connection of optional external scale factor adjustment pot. ³Connect optional filter capacitor between pin 1 and pin 2 (see Figure 2). Pin 1 is

protected for shorts to ground and the positive supply voltage. Pin 1 is not protected for negative voltages greater than 1 volt.

⁴ Protected for short circuit to ground and/or supply voltage.

⁵ Output offset voltage may be adjusted to zero. See Figure 2 and Figure 3 for connection diagram of optional $20k\Omega$ pot. Adjustment range; $\pm 20mV$.

⁶ Recommended power supply: Analog Devices' Model 915,

Applying The True RMS-to-DC Converter

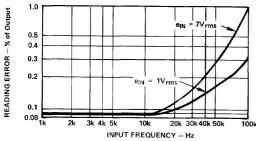


Figure 4. Error vs. Frequency, Sinewave Input

LOW FREQUENCY PERFORMANCE VERSUS FILTER TIME CONSTANT

Shown in Figure 5 is a plot of reading error versus frequency with the external filter capacitor (C_f) as a parameter. This capacitor is selected to increase the filter time constant to reduce output ripple for low frequency measurements. Accuracy at high frequencies is not affected by C_f .

In selecting the external filter capacitor, the lowest frequency component of the input signal should be determined. An averaging time constant (τ) of approximately 10 times the period of this frequency should then be selected. The averaging time constant of model 440 is determined from the following relation:

$$\tau$$
 (ms) = 10 + 50 C_f (μ F)

Low leakage capacitors, such as tantalum electrolytic are recommended. Figure 5 shows curves for C_f values of 0, 1, 10 and $33\mu F$ and may be used to bracket the reading errors when other values are selected.

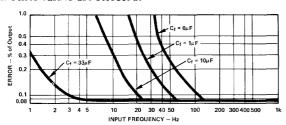


Figure 5. Error vs. Frequency, Sinewave Input SETTLING TIME RESPONSE VERSUS FILTER TIME CONSTANT

Although there is no upper limit on how large a capacitor may be used to reduce ripple at low frequencies, there is a practical limitation due to increased settling time for step changes in RMS level occurring at the input. Figure 6 shows curves of settling time to 1% accuracy for increasing and decreasing one volt RMS input step changes. Increasing step changes (10mV to $1V_{rms}$) settle to approximately three time constants (τ (ms) = $10 + 50C_f$); decreasing step changes ($1V_{rms}$ to 10mV) settle to approximately 5 time constants. The designer must consider optimizing settling time and low frequency error in selecting the external filter capacitor.

RMS MEASUREMENT ACCURACY AND CREST FACTOR

Crest factor is frequently understated in importance for RMS measurements, yet it is key to determining the accuracy of a true RMS measurement on a specific waveform. Crest factor is defined as the ratio of the peak signal amplitude to the RMS value (C.F. = V_p/V_{rms}). Figure 7 shows crest factor and RMS values for most frequently encountered waveforms. The examples shown illustrate that most common waveforms have relatively low crest factors (<2). Waveforms such as low duty cycle pulse trains have high crest factors (e.g. for a 1% duty cycle pulse train, crest factor is 10).

The peak signal input for model 440 is rated at $\pm 10V$. Crest factor, peak input voltage and RMS level are related by the crest factor definition; C.F. = V_p/V_{rms} . Therefore, for a particular waveform the max RMS input range may be determined from the signal crest factor. For example, for a sinewave, crest factor is 1.41. Therefore V_{rms} (max input) = $10V/1.41 = 7V_{rms}$.

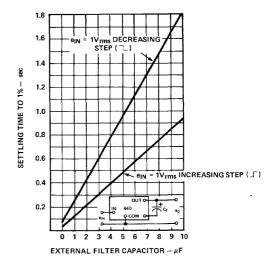


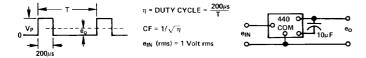
Figure 6. Settling Time vs. Filter Capacitor (C_f)

INPUT	CREST FACTOR	RMS	RMS O	UTPUT	
WAVEFORM	(= V _p /V _{rms})	OUTPUT	FOR V _p =	10 VOLTS	
SINE WAVE	√2 (= 1.414)	$\frac{v_p}{\sqrt{2}}$	7∨ _{rms}		
SYMMETRICAL SQUARE WAVE (OR DC)	1	Vp	10V _{rms}		
TRIANGULAR WAVE	√3 (= 1.732)	$\frac{V_p}{\sqrt{3}}$	5.77	V _{rms}	
GAUSSIAN II	EXAMPLE: C.F. > 4 HAS A PROBABILITY 100 OF < 0.01%	RMS	C.F. 1 2 3 4 5	V _{rms} 10 5 3.3 2.5	
PULSE TRAIN V_p V_p	$\begin{array}{c cccc} & 1 & & \\ \hline & & C.F. \\ \hline & 1 & 1 \\ \hline & 1/4 & 2 \\ \hline & 1/64 & 8 \\ \hline & 1/100 & 10 \\ \hline \end{array}$	$V_{p}\sqrt{\eta}$ V_{p} $0.5 V_{p}$ $0.25 V_{p}$ $0.125 V_{p}$ $0.1 V_{p}$	10 V _t 5 V _{tt} 2.5 V	ns rms /rms	
SINE-SQUARED	√8/3 (= 1.633)	V _p 1.63	1 V _{rms} 6.13V _{rms}		
SCR OUTPUT	1.68	V _p 1.68	5.95V _{rms}		
SAWTOOTH PULSE	$\sqrt{\frac{3}{n}}$	$V_p\sqrt{rac{\overline{\eta}}{3}}$	10 \	/ 1/3	

Figure 7. Crest Factor and RMS Values for a Wide Class of Waveforms

ACCURACY AND SIGNAL CREST FACTOR

Shown in Figure 8 is a curve of reading error for model 440 with a one volt rms pulse train with variable duty cycle and peak amplitude. In this curve, pulse width (200 μ s) and RMS level (1 Volt) are held constant. The pulse train was selected because of its ability to generate a wide range of crest factors by varying the duty cycle (C.F. = $1/\sqrt{\eta}$). At a crest factor of 10, the peak input amplitude is 10 Volts (V_p = (C.F.) (V_{rms}). Therefore a one volt RMS level was selected to provide reading errors for crest factors from 1 to 10 (V_p from 1 to 10 Volts). Figure 8 may be used to estimate the reading error of the general class of waveform shown in Figure 7.



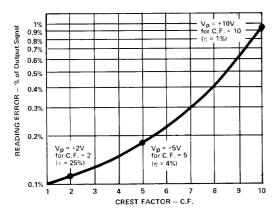


Figure 8. Error vs. Crest Factor

ACCURACY AND PULSE WIDTH

To relate error versus pulse width response, Figure 9 has been developed wherein crest factor and rms level are presented as parameters. Because of the extremely high frequency harmonic content in narrow pulse widths, the curves of Figure 9 present a worst case indication of error performance with frequency for the class of waveform shown in Figure 7. Model 440 may be used for pulse widths as small as 50µs with negligible additional error.

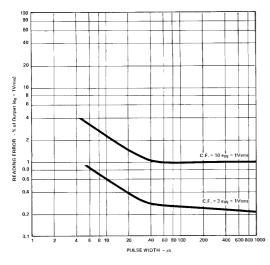


Figure 9. Error vs. Pulse Width and Crest Factor for Pulse Train

OPTIONAL EXTERNAL ADJUSTMENT PROCEDURE

Optional external trimming consists of two adjustments: output offset and scale factor. By the use of these two trims, overall accuracy may be improved significantly. To adjust output offset voltage, connect a 20k trim pot as shown in Figure 2 and short the input to common. Adjust for zero output voltage. To trim scale factor, connect a 5k trim pot as shown in Figure 2 and apply a positive DC input signal at the desired full scale RMS level (e.g., +1.000V). Adjust the scale factor pot until the output is equal to the input. Reverse the input polarity and measure the error in output level. Readjust the scale factor pot for lowest error for both polarity inputs.

When model 440 is used to perform mean square measurements, the output offset voltage may be adjusted to zero by means of a $20 \mathrm{k}\Omega$ potentiometer connected as shown in Figure 3. To trim the output to zero, apply a +10V reference voltage to pin 6, and connect the input to signal common. Adjust the offset potentiometer for zero output.

TRUE RMS DIGITAL PANEL METER APPLICATION

Model 440 may be used to provide an economical, true RMS measurement capability for modular digital panel meters (DPM). Figure 10 illustrates an application of model 440 with a popular 3½ digit line powered DPM (Analog Devices' model AD2006). The low power requirements of model 440 allow the use of the DPM's external power outputs (±15V @ 10mA), eliminating the need for a separate power supply for model 440. The input resistor (R_1) provides the capability to easily set the nominal full scale input voltage to the DPM at 1 Volt for the peak input signal to be measured (Ein). For example, to measure 115VAC line voltage, R₁ would be selected for a 100:1 attenuation ratio ($R_1 = 100 (R_{in}) = 830k$. The external filter capacitor is selected to achieve desired accuracy for the input frequency range; a 1µF would give rated accuracy for 50-60Hz line frequencies (see Figure 5). For best accuracy, the scale factor potentiometer (R2) would be adjusted with a precision reference voltage input; a 100VDC signal may be used with the 830k Ω .

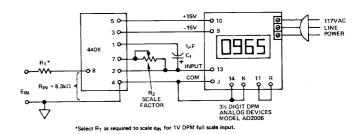


Figure 10. True RMS DPM Application Using AD2006 DPM Internal Power to Operate Model 440K